

## An Efficient Clustering Algorithm for Image Segmentation

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**Abstract:** Gray-level clustering is an important procedure in image processing, which reduces the gray-level of an image. In order to display an image with high gray level in a screen with lower gray level, a good gray-level clustering algorithm is necessary to complete this job. Based on the mean value and standard deviation of histogram within a sub-interval, a novel recursive algorithm for solving the gray-level reduction is proposed in this paper. It divides the sub-interval recursively until the difference between original image and clustered image within a given threshold. Experiments are carried out for some samples with high gray level to demonstrate the computational advantage of the proposed method.

**Key words:** Gray-level clustering • Image processing • Clustering algorithm • Image segmentation • Histogram

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### INTRODUCTION

The main purpose of gray-level clustering is to reduce a high gray-level image into a lower gray-level image. A clustered image can then be used in many applications. For example, satellite image clustering [1] is used for classification of geology, the measure of area on forest, or scope of cultivated land. In image compression [2] application, a clustered image might reach a higher compression rate. The application for magnetic resonance imaging [3], the injured area of apple is obtained after clustered. In text classification [4] application, text is easy to be extracted from a clustered image. Since the gray-level and resolution of a screen in a cell phone, MP4, or PDA is usually lower than that of a PC, to reduce the gray-level and resolution of an image is necessary for displaying on these equipments.

There are two types of image clustering. The first type is based on the gray-level. It includes single thresholding [5] and multi-thresholding [5-11] on gray-level. Single thresholding just transforms original image to binary image. Multi-thresholding classifies the gray-level into several intervals. Otsu's method [5] is the most classic method in multi-thresholding. However, it takes a lot of time to complete the multi-thresholding. Thus, Arora [11] proposed a quick multi-thresholding algorithm to solve this problem in 2008.

The second type of image clustering is based on clustering technology. K-means algorithm [12-13] is the

classic method in solving this problem. But, the number of clusters and the initial set of each cluster center must be set by human. Final output set of each cluster center in K-means algorithm will be the set of gray-level for each cluster. Since time needed for K-means algorithm is too high to be implemented, Dong proposed a fast K-means algorithm [13] in 2006. Based on two-layer pyramid data structure, Dong's algorithm finds the image cluster from the lower resolution image and then extends it to the higher resolution image.

With combining the methods of first type and second type, a precise and fast gray-level clustering algorithm is proposed in this paper. The first type method used in this paper is Arora [11] algorithm, which is used to get the number of clusters and the initial set of each cluster center. Then, K-means clustering algorithm is introduced to update the set of each cluster center until all centers are not changed. Therefore, a precise and fast gray-level clustering algorithm is created [14-15].

The rest of this paper is organized as follows. The proposed algorithm of gray-level clustering is presented in next section. Section 4 applies the proposed algorithm and the compared algorithms to several sample images. Concluding remarks and potential applications are provided in Section 5.

**Proposed Algorithm:** An  $M \times N$  resolution digital image may be defined as a two-dimensional function where  $x$  and  $y$  are spatial coordinates and the amplitude of  $F$  at any

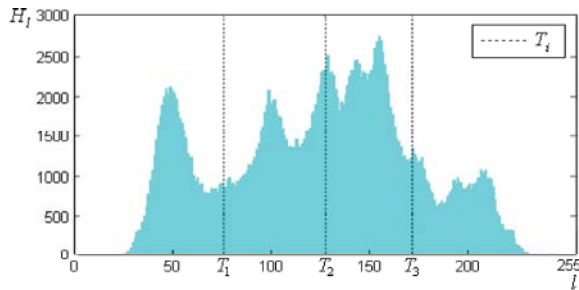


Fig. 1: Example of a histogram partitioned into 4 sub-intervals

pair of coordinates  $(x, y)$  is the gray level of the image at that point [18]. Thus, we use  $F(x, y)$  to represent an original input image.

Then the array of an original input image  $F(x, y)$  is:

```
(1,0) (1,1) (1, 1)
(1,0) (1,1) (1, 1)
(0,0) (0,1) (0, 1)
```

A set of gray-level is clustered by the proposed algorithm based on the histogram. That is, a histogram is partitioned by proposed algorithm into  $n$  sub-intervals [16]. According to the intensity of gray-level from small to large, sub-intervals are numbered as  $0, 1, 2, \dots, n-1$ . Figure 1 shows an example of histogram partitioned into 4 sub-intervals, i.e.,  $n=4$ . Let  $T_i$  be mult-threshold between sub-intervals, where  $i = 0, 1, 2, \dots, n$ .

The values of mult-threshold  $T_0, T_1, T_2, T_3$  and  $T_4$  are  $0, 76, 128, 172$  and  $256$ , respectively, shown in Figure 1. The mult-thresholds partition gray-level into 4 sub-intervals, i.e., sub-intervals  $[0, 76), [76, 128), [128, 172)$  and  $[172, 256)$ , respectively. Let  $V_i$  be the mean value of gray-level in sub-interval  $i$ , where  $i = 0, 1, 2, \dots, n-1$ . There are 4 mean values  $V_0, V_1, V_2$  and  $V_3$  in Figure 1, which are  $54, 106, 149$  and  $195$ , respectively.

In order to measure the visual quality of clustered image, peak signal to noise ratio ( $PSNR$ ) is introduced in the proposed algorithm.  $PSNR$  [11] is expressed as:

$$PSNR = 20 \log_{10} (255 / RMSE)$$

The unit of  $PSNR$  is dB. The higher the  $PSNR$  is, the more similar between the clustered image and original image. We use Arora [11] algorithm to derive the number of clusters and the initial set of each cluster center. And then, K-means clustering algorithm [12-13] is introduced to update the set of each cluster center until all centers are not changed.

With combining the Arora algorithm and K-means algorithm, a precise and fast gray-level clustering algorithm is proposed in this paper. That is, Effective Multilevel Thresholding Algorithm.

Input: Original image  $F(x, y)$   
 Output: Thresholded image  $G(x, y)$   
 set  $n = 2, a = 0, b = 256, PSNR = 0$   
 calculate  $\mu$  and  $\sigma$  of histogram in interval  $[a, b)$   
 set  $T_0 = 0, T_1 = \mu, T_2 = 256$

Loop-1:  
 $a = T_{n/2} - \sigma$  and  $b = T_{n/2} + \sigma$   
 $n = n + 2$   
 calculate  $\mu$  and  $\sigma$  of histogram in interval  $[a, b)$   
 for  $i = n$  down to  $n/2 + 2$  do  $T_i = T_{i-2}$   
 set  $T_{n/2} = \mu, T_{n/2-1} = a$  and  $T_{n/2+1} = b$   
 for  $i = 0$  to  $n-1$  do  
 calculate  $\mu$  of histogram in interval  $[T_i, T_{i+1})$   
 set  $V_i = \mu$   
 calculate  $RMSE$  and  $PSNR$   
 repeat Loop-1 until the increment of  $PSNR < 0.1$   
 Loop-2:  
 for  $i = 0$  to  $n-2$  do  
 calculate  $\mu$  of histogram in interval  $[V_i, V_{i+1})$   
 set  $T_{i+1} = \mu$   
 for  $i = 0$  to  $n-1$  do  
 calculate  $\mu$  of histogram in interval  $[T_i, T_{i+1})$   
 set  $V_i = \mu$   
 repeat Loop-2 until all  $V_i$  are not changed  
 For each pixel  $(x, y)$   
 $G(x, y) = V_i$ , if  $F(x, y)$  lies in interval  $[T_i, T_{i+1})$

Figure 2(a) is original image of Lena. Its gray-level is 256 and its resolution is 512 by 512. Table 1 lists the values of  $n, T_i, V_i$  and  $PSNR$  for each loop during processing in the proposed algorithm with the image of Figure 2(a).



Fig. 2: Lena images of (a) original image with 256 gray level  
 (b) clustered image with 12 gray-level

Table 1: Processing for Lena

$N$	$T_i$	PSNR
Loop-1:		
2	$V_i$ : 81, 161	
	$T_i$ : 0, 124, 256	19.66
4	$V_i$ : 54, 106, 149, 195	
	$T_i$ : 0, 76, 128, 172, 256	25.95
6	$V_i$ : 54, 92, 118, 142, 161, 195	
	$T_i$ : 0, 76, 103, 129, 153, 172, 256	28.71
8	$V_i$ : 54, 92, 109, 123, 137, 149, 161, 195	
	$T_i$ : 0, 76, 103, 115, 129, 143, 153, 172, 256	29.53
10	$V_i$ : 54, 92, 109, 119, 126, 132, 140, 149, 161, 195	
	$T_i$ : 0, 76, 103, 115, 122, 128, 136, 143, 153, 172, 256	29.70
12	$V_i$ : 54, 92, 109, 119, 124, 126, 130, 134, 140, 149, 161, 195	
	$T_i$ : 0, 76, 103, 115, 122, 124, 127, 132, 136, 143, 153, 172, 256	29.72
Loop-2:		
12	$V_i$ : 47, 70, 95, 111, 124, 134, 144, 154, 164, 174, 195, 211	
	$T_i$ : 0, 56, 84, 103, 118, 129, 139, 149, 158, 170, 186, 203, 256	34.28

From Table 1, it is easy to see that the final  $n$  is 12 and PSNR is 34.28 dB. Figure 2(b) shows the clustered image derived by the proposed algorithm. Although the gray-level in Figure 2(b) is 12, it is really similar to original image. Therefore, the proposed algorithm can be used to the equipment with lower gray-level displaying screen.

**RESULTS**

In order to prove the usefulness of the proposed algorithm, four different images with 512x512 resolution are used for experiments. Figures 3(a), 3(b), 3(c) and 3(d) are original images named Baboon, Jet, Peppers and Washbowl, respectively. The compared methods used in this paper are K-means algorithm [12], Dong's algorithm [13] and Arora's algorithm [11]. Since K-means algorithm and Dong's algorithm need the initial  $n$  and the initial set of each cluster center, we use the outputs of  $n$  and  $V_i$  from Arora's algorithm. Figures 4(a), 4(b) and 4(c) are the clustered images making by K-means algorithm [12], Dong's algorithm [13], 260 and Arora's algorithm [11], respectively. Compared them to Figure 2(b), it is found that there are blocks in the clustered images of compared methods. For examples, block images appeared on Lena's shoulder, forehead and hat.

Table 2: Methods Compared

Image Method	PSNR	Time(ms)
Lena K-means algorithm	33.14	4340
Dong's algorithm	33.57	3304
Arora's algorithm	29.72	316
Proposed algorithm	34.28	317
Baboon K-means algorithm	33.27	5722
Dong's algorithm	33.43	3066
Arora's algorithm	29.03	322
Proposed algorithm	33.67	323
Jet K-means algorithm	30.79	5207
Dong's algorithm	30.79	3005
Arora's algorithm	26.29	281
Proposed algorithm	31.16	282
Peppers K-means algorithm	31.78	3156
Dong's algorithm	32.35	2719
Arora's algorithm	28.25	318
Proposed algorithm	32.45	320
Washbowl K-means algorithm	32.96	5205
Dong's algorithm	32.81	2989
Arora's algorithm	28.72	307
Proposed algorithm	33.43	308

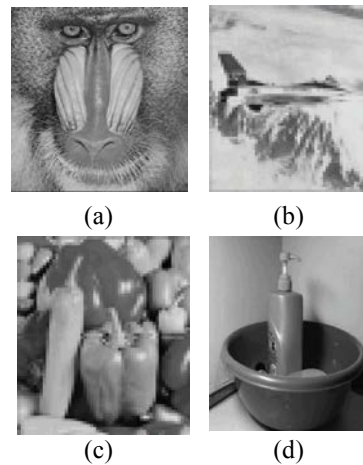


Fig. 3: Original images (a) Baboon (b) Jet (c) Peppers (d) Washbowl

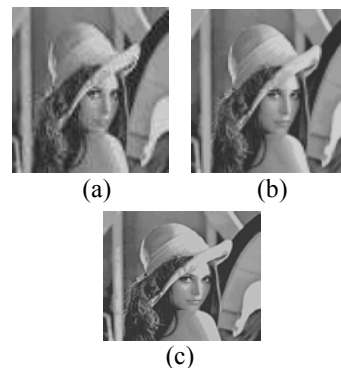


Fig. 4: Clustered images using (a) K-means algorithm (b) Dong's algorithm (c) Arora's algorithm

Both of the compared algorithms and the proposed algorithm are implemented with Matlab and run on a personal computer with a AMD K8-3.2G processor, 1 GB RAM and 512 KB cache. Table 2 lists the values of *PSNR* and times needed of each method for the testing images Lena, Baboon, Jet, Peppers and Washbowl. From Table 2, based on the same clustered number, it is obvious to see that the proposed algorithm builds the clustered images with the highest values of *PSNR* among the other methods. The *PSNR*s of the proposed algorithm for images Lena, Baboon, Jet, Peppers and Washbowl are 34.28, 33.67, 31.16, 32.45 and 33.43, respectively. Although the time needed of Arora's algorithm [11] is the lowest over other methods, its *PSNR*s are the lowest in all testing images [17]. The speed of the proposed algorithm is also extremely close to that of Arora's algorithm [11], which is faster than K-means algorithm [12] and Dong's algorithm [13].

## CONCLUSIONS

Based on the mean value, standard deviation and *PSNR*, a new gray-level clustering algorithm is proposed in this paper for image segmentation. Evaluation results show the proposed algorithm succeeds in deriving clustered images. The clustered image built by the proposed algorithm is extremely close to that of original image [18-20]. The algorithm also reduces the *RMSE* much more than other schemes, which makes it better suited for real equipment with lower gray level displaying screen.

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