

Focal Curve of Biharmonic Curves in the Special Three-Dimensional ϕ -Ricci Symmetric Para-Sasakian Manifold P

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Abstract: In this paper, we study biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P. Finally, we construct parametric equations of focal curve of biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P.

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Key words: Biharmonic curve • Para-Sasakian manifold • Focal curve

INTRODUCTION

The differential geometry of space curves is a classical subject which usually relates geometrical intuition with analysis and topology. For any unit speed curve γ , the focal curve C_γ is defined as the centers of the osculating spheres of γ . Since the center of any sphere tangent to γ at a point lies on the normal plane to γ at that point, the focal curve of γ may be parameterized using the Frenet frame $(\mathbf{t}(s), \mathbf{n}_1(s), \mathbf{n}_2(s))$ of γ as follows:

$$C_\gamma(s) = (\gamma + c_1 \mathbf{n}_1 + c_2 \mathbf{n}_2)(s),$$

Where the coefficients c_1, c_2 are smooth functions that are called focal curvatures of γ .

The aim of this paper is to study biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P.

A smooth map $\phi: N \rightarrow M$ is said to be biharmonic if it is a critical point of the bienergy functional:

$$E_2(\phi) = \int_N \frac{1}{2} |T(\phi)|^2 dv_h,$$

Where $T(\phi) := \text{tr} \nabla^\phi d\phi$ is the tension field of ϕ

The Euler-Lagrange equation of the bienergy is given by $T_2(\phi) = 0$. Here the section $T_2(\phi)$ is defined by

$$T_2(\phi) = -\Delta_\phi T(\phi) + \text{tr} R(\phi, d\phi) d\phi, \quad (1.1)$$

and called the bitension field of ϕ . Non-harmonic biharmonic maps are called proper biharmonic maps.

In this paper, we study biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P. Finally, we construct parametric equations of focal curve of biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P.

Preliminaries: An n -dimensional differentiable manifold M is said to admit an almost para-contact Riemannian structure (ϕ, ξ, η, g) , where ϕ is a ξ tensor field, ξ is a vector field, η is a 1-form and g is a Riemannian metric on M such that

$$\phi \xi = 0, \eta(\xi) = 1, g(X, \xi) = \eta(X), \quad (2.1)$$

$$\phi^2(X) = X - \eta(X)\xi, \quad (2.2)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad (2.3)$$

for any vector fields X, Y on M .

In addition, if (ϕ, ξ, η, g) satisfy the equations

$$d\eta = 0, \nabla_X \xi = \phi X, \quad (2.4)$$

$$(\nabla_X \phi)Y = -g(X, Y)\xi - \eta(Y)X + 2\eta(X)\eta(Y)\xi, X, Y \in \chi(M), \quad (2.5)$$

then M is called a para-Sasakian manifold or, briefly a P -Sasakian manifold. In particular, a P -Sasakian manifold M is called a special para-Sasakian manifold or briefly a SP -Sasakian manifold if M admits a 1-form η satisfying

$$(\nabla_X \eta)Y = -g(X, Y) + \eta(X)\eta(Y). \quad (2.6)$$

It is known [16] that in a P -Sasakian manifold the following relations hold:

$$S(X, \xi) = -(n-1)\eta(X),$$

$$Q\xi = -(n-1)\xi,$$

$$R(X, Y)\xi = \eta(X)Y - \eta(Y)X,$$

$$R(\xi, X)Y = \eta(Y)X - g(X, Y)\xi,$$

$$R(\xi, X)\xi = X - \eta(X)\xi,$$

$$\eta(R(X, Y)Z) = \eta(Y)g(X, Z) - \eta(X)g(Y, Z),$$

$$S(\phi X, \phi Y) = S(X, Y) + (n-1)\eta(X)\eta(Y),$$

for any vector fields X, Y, Z on M .

A para-Sasakian manifold is said to be Einstein if the Ricci tensor S is of the form

$$S(X, Y) = \lambda g(X, Y)$$

Where λ is a constant.

Special Three-Dimensional ϕ -Ricci Symmetric Para-Sasakian Manifold P

Definition 3.1: A para-Sasakian manifold M is said to be locally ϕ -symmetric if

$$\phi^2((\nabla_{\#} R)(X, Y)Z) = 0,$$

for all vector fields X, Y, Z, W orthogonal to ξ . This notion was introduced by Takahashi [16], for a Sasakian manifold.

Definition 3.2: A para-Sasakian manifold M is said to be ϕ -symmetric if

$$\phi^2((\nabla_{\#} R)(X, Y)Z) = 0,$$

for all vector fields X, Y, Z, W on M .

Definition 3.3: A para-Sasakian manifold M is said to be ϕ -Ricci symmetric if the Ricci operator satisfies

$$\phi^2((\nabla_X Q)(Y)) = 0,$$

for all vector fields X and Y on M and $S(X, Y) = g(QX, Y)$.

If X, Y are orthogonal to ξ , then the manifold is said to be locally ϕ -Ricci symmetric.

We consider the three-dimensional manifold

$$P = \left\{ (x^1, x^2, x^3) \in \mathbb{R}^3 : (x^1, x^2, x^3) \neq (0, 0, 0) \right\},$$

Where (x^1, x^2, x^3) are the standard coordinates in \mathbb{R}^3 . We choose the vector fields

$$\mathbf{e}_1 = e^{x^1} \frac{\partial}{\partial x^2}, \mathbf{e}_2 = e^{x^1} \left(\frac{\partial}{\partial x^2} - \frac{\partial}{\partial x^3} \right), \mathbf{e}_3 = -\frac{\partial}{\partial x^1} \quad (3.1)$$

are linearly independent at each point of P . Let g be the Riemannian metric defined by

$$g(\mathbf{e}_1, \mathbf{e}_1) = g(\mathbf{e}_2, \mathbf{e}_2) = g(\mathbf{e}_3, \mathbf{e}_3) = 1, \quad (3.2)$$

$$g(\mathbf{e}_1, \mathbf{e}_2) = g(\mathbf{e}_2, \mathbf{e}_3) = g(\mathbf{e}_1, \mathbf{e}_3) = 0.$$

Let η be the 1-form defined by

$$\eta(Z) = g(Z, \mathbf{e}_3) \text{ for any } Z \in \chi(P).$$

Let be the (1,1) tensor field defined by

$$\phi(\mathbf{e}_1) = \mathbf{e}_2, \phi(\mathbf{e}_2) = \mathbf{e}_1, \phi(\mathbf{e}_3) = 0. \quad (3.3)$$

Then using the linearity of g and η we have

$$\eta(\mathbf{e}_3) = 1, \quad (3.4)$$

$$\phi^2(Z) = Z - \eta(Z)\mathbf{e}_3, \quad (3.5)$$

$$g(\phi Z, \phi W) = g(Z, W) - \eta(Z)\eta(W) \quad (3.6)$$

for any $Z, W \in \chi(P)$. Thus for $\mathbf{e}_3 = \xi$, (ϕ, ξ, η, g) defines an almost para-contact metric structure on P .

Let ∇ be the Levi-Civita connection with respect to g . Then, we have

$$\mathbf{e}_1, \mathbf{e}_2] = 0, [\mathbf{e}_1, \mathbf{e}_3] = \mathbf{e}_1, [\mathbf{e}_2, \mathbf{e}_3] = \mathbf{e}_2.$$

Taking $\mathbf{e}_3 = \xi$ and using the Koszul's formula, we obtain

$$\begin{aligned} \nabla_{\mathbf{e}_1} \mathbf{e}_1 &= -\mathbf{e}_3, \nabla_{\mathbf{e}_1} \mathbf{e}_2 = 0, \nabla_{\mathbf{e}_1} \mathbf{e}_3 = \mathbf{e}_1, \\ \nabla_{\mathbf{e}_2} \mathbf{e}_1 &= 0, \nabla_{\mathbf{e}_2} \mathbf{e}_2 = -\mathbf{e}_3, \nabla_{\mathbf{e}_2} \mathbf{e}_3 = \mathbf{e}_2, \end{aligned} \quad (3.7)$$

$$\nabla_{\mathbf{e}_3} \mathbf{e}_1 = 0, \nabla_{\mathbf{e}_3} \mathbf{e}_2 = 0, \nabla_{\mathbf{e}_3} \mathbf{e}_3 = 0.$$

Moreover we put

$$R_{ijk} = R(\mathbf{e}_i, \mathbf{e}_j)\mathbf{e}_k, \quad R_{jkl} = R(\mathbf{e}_i, \mathbf{e}_j, \mathbf{e}_k, \mathbf{e}_l),$$

Where the indices i, j, k and l take the values 1, 2 and 3.

$$R_{122} = -\mathbf{e}_1, R_{133} = -\mathbf{e}_1, R_{233} = -\mathbf{e}_2,$$

and

$$R_{1212} = R_{1313} = R_{2323} = 1 \quad (3.8)$$

Biharmonic Curve in the Special Three-Dimensional ϕ -Ricci Symmetric Para-Sasakian Manifold P: Let us consider biharmonicity of curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P. Let $\{\mathbf{t}, \mathbf{n}_1, \mathbf{n}_2\}$, be the Frenet frame field along γ . Then, the Frenet frame satisfies the following Frenet-Serret equations:

$$\nabla_t \mathbf{t} = \kappa \mathbf{n}_1,$$

$$\nabla_t \mathbf{n}_1 = -\kappa \mathbf{t} + \tau \mathbf{n}_2 \quad (4.1)$$

$$\nabla_t \mathbf{n}_2 = -\tau \mathbf{n}_1,$$

Where κ is the curvature of γ and τ its torsion and

$$g(\mathbf{t}, \mathbf{t}) = 1, g(\mathbf{n}_1, \mathbf{n}_1) = 1, g(\mathbf{n}_2, \mathbf{n}_2) = 1, \quad (4.2)$$

$$g(\mathbf{t}, \mathbf{n}_1) = g(\mathbf{t}, \mathbf{n}_2) = g(\mathbf{n}_1, \mathbf{n}_2) = 0.$$

With respect to the orthonormal basis $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$, we can write

$$\mathbf{t} = t_1 \mathbf{e}_1 + t_2 \mathbf{e}_2 + t_3 \mathbf{e}_3,$$

$$\mathbf{n}_1 = n_1^1 \mathbf{e}_1 + n_1^2 \mathbf{e}_2 + n_1^3 \mathbf{e}_3, \quad (4.3)$$

$$\mathbf{n}_2 = \mathbf{t} \times \mathbf{n}_1 = n_2^1 \mathbf{e}_1 + n_2^2 \mathbf{e}_2 + n_2^3 \mathbf{e}_3.$$

Theorem 4.1: (see [12]) $\gamma: I \rightarrow P$ is a biharmonic curve if and only if

$$\begin{aligned} \kappa &= \text{constant} \neq 0, \\ \kappa^2 + \tau^2 &= 1, \\ \tau' &= 0. \end{aligned} \quad (4.4)$$

Proof: Using Frenet formulas (4.1), we have (4.4).

Theorem 4.2: [12] All of biharmonic curves in the special three-dimensional ϕ -Ricci symmetric para-Sasakian manifold P are helices.

Theorem 4.3: [12] Let $\gamma: I \rightarrow P$ be a unit speed non-geodesic curve with constant curvature. Then, the parametric curve. Then, the parametric equations of γ are

$$x^1(s) = -s \cos \varphi + a_1,$$

$$\begin{aligned} x^2(s) &= a_2 - \frac{\sin^3 \varphi}{\kappa^2 - \sin^4 \varphi} e^{-s \cos \varphi + a_1} (\Pi + \cos \varphi) \cos[\Pi s + a] \\ &+ [-\Pi + \cos \varphi] \sin[\Pi s + a], \end{aligned} \quad (4.5)$$

$$\begin{aligned} x^3(s) &= C_3 - \frac{\sin^3 \varphi}{\kappa^2 - \sin^4 \varphi} e^{-s \cos \varphi + C_1} (-\cos \varphi \cos[\Pi s + a] \\ &+ [\Pi s + C] \sin[\Pi s + a]), \end{aligned}$$

Where a, a_1, a_2, a_3 are constants of integration and

$$\Pi = \frac{\sqrt{\kappa^2 - \sin^2 \varphi}}{\sin \varphi}.$$

Focal Curve of Biharmonic Curves in the Special Three-dimensional ϕ -Ricci Symmetric Para-sasakian Manifold P:

For a unit speed curve γ , the curve consisting of the centers of the osculating spheres of γ is called the parametrized focal curve of γ . The hyperplanes normal to γ at a point consist of the set of centers of all spheres tangent to γ at that point. Hence the center of the osculating spheres at that point lies in such a normal plane. Therefore, denoting the focal curve by C_γ we can write

$$C_\gamma(s) = (\gamma + c_1 \mathbf{n}_1 + c_2 \mathbf{n}_2)(s) \quad (5.1)$$

Where the coefficients c_1, c_2 are smooth functions of the parameter of the curve γ , called the first and second focal curvatures of γ , respectively. Further, the focal curvatures c_1, c_2 are defined by

$$c_1 = \frac{1}{\kappa}, c_2 = \frac{c_1'}{\tau}, \kappa \neq 0, \tau \neq 0. \quad (5.2)$$

Lemma 5.1: Let $\gamma: I \rightarrow P$ be a unit speed biharmonic curve and C_γ its focal curve on P. Then,

$$c_1 = \frac{1}{\kappa} = \text{constant and } c_2 = 0. \quad (5.3)$$

Proof: Using (3.3) and (5.2), we get (5.3).

Lemma 5.2: Let $\gamma: I \rightarrow P$ be a unit speed biharmonic curve and C_γ its focal curve on P. Then,

$$C_\gamma(s) = (\gamma + c_1 \mathbf{n}_1)(s) \quad (5.4)$$

Theorem 5.3: Let $\gamma : I \rightarrow \mathbb{P}$ be a biharmonic curve parametrized by arc length. If C_γ is a focal curve of γ , then the parametric equations of C_γ are

$$\begin{aligned}\tilde{x}^1(s) &= -\frac{c_1 \sin^2 \varphi}{2\kappa} s^2 + (\bar{a}_1 - \cos \varphi) s + \bar{a}_2 + a_1 \\ \tilde{x}^2(s) &= a_2 - \frac{\sin^3 \varphi}{\kappa^2 - \sin^4 \varphi} e^{-s \cos \varphi + C_1} (\Pi \cos[\Pi s + a] + [-\Pi + \cos \varphi] \sin[\Pi s + a]) \\ &\quad + \frac{c_1 \sin \varphi}{\kappa} e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} (\Pi \sin[\Pi s + a] + \cos \varphi \cos[\Pi s + a]) \\ &\quad + \frac{c_1 \sin \varphi}{\kappa} e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} (-\Pi \cos[\Pi s + a] + \cos \varphi \sin[\Pi s + a]), \\ \tilde{x}^3(s) &= a_3 - \frac{\sin^3 \varphi}{\kappa^2 - \sin^4 \varphi} e^{-s \cos \varphi + C_1} (-\cos \varphi \cos[\Pi s + a] + [\Pi s + a] \sin[\Pi s + a]) \\ &\quad - \frac{c_1 \sin \varphi}{\kappa} e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} (-\Pi \cos[\Pi s + a] + \cos \varphi \sin[\Pi s + a]),\end{aligned}\tag{5.5}$$

Where $a, \bar{a}_1, \bar{a}_2, a_1, a_2, a_3$ are constants of integration and $\Pi = \frac{\sqrt{\kappa^2 - \sin^2 \varphi}}{\sin \varphi}$.

Proof: Let C_γ is a focal curve of γ Recalling [12], we have

$$\mathbf{T} = \sin \varphi \cos[\Pi s + a] \mathbf{e}_1 + \sin \varphi \sin[\Pi s + a] \mathbf{e}_2 + \cos \varphi \mathbf{e}_3,\tag{5.6}$$

Where $\Pi = \frac{\sqrt{\kappa^2 - \sin^2 \varphi}}{\sin \varphi}$ and a is a constant of integration.

On the other hand, using first equation of (4.3) we get

$$\nabla_{\mathbf{t}} \mathbf{t} = (t'_1 + t_1 t_3) \mathbf{e}_1 + (t'_2 + t_2 t_3) \mathbf{e}_2 + \left(t'_3 - (t_1^2 - t_2^2) \right) \mathbf{e}_3.\tag{5.7}$$

From (4.1) and (5.6), we get

$$\begin{aligned}\nabla_{\mathbf{t}} \mathbf{t} &= \sin \varphi (-\Pi \sin[\Pi s + a] + \cos \varphi \cos[\Pi s + a]) \mathbf{e}_1 + \\ &\quad \sin \varphi (\Pi \cos[\Pi s + a] + \cos \varphi \sin[\Pi s + a]) \mathbf{e}_2 - \sin^2 \varphi \mathbf{e}_3,\end{aligned}\tag{5.8}$$

Where $\Pi = \frac{\sqrt{\kappa^2 - \sin^2 \varphi}}{\sin \varphi}$.

Taking into account Frenet formulas (4.1), we derive that

$$\begin{aligned}\mathbf{n}_1 &= \frac{1}{\kappa} \nabla_{\mathbf{t}} \mathbf{t} = \frac{1}{\kappa} [(\Pi \sin \varphi \sin[\Pi s + a] + \cos \varphi \sin \varphi \cos[\Pi s + a]) \mathbf{e}_1 \\ &\quad + (-\Pi \sin \varphi \cos[\Pi s + a] + \cos \varphi \sin \varphi \sin[\Pi s + a]) \mathbf{e}_2 - \sin^2 \varphi \mathbf{e}_3].\end{aligned}\tag{5.9}$$

Substituting (3.1) in (5.9), we arrive at

$$\begin{aligned} \mathbf{n}_1 = & \frac{1}{\kappa} \left(-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2, \right. \\ & e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} \left(\Pi \sin \varphi \sin[\Pi s + a] + \cos \varphi \sin \varphi \cos[\Pi s + a] \right) + \\ & e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} \left(-\Pi \sin \varphi \cos[\Pi s + a] + \cos \varphi \sin \varphi \sin[\Pi s + a] \right), - \\ & \left. e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} \left(-\Pi \sin \varphi \cos[\Pi s + a] + \cos \varphi \sin \varphi \sin[\Pi s + a] \right) \right), \end{aligned} \quad (5.10)$$

Where \bar{a}_1, \bar{a}_2 are constants of integration.

Next, we substitute (5.10) and (4.5) into (5.4), we get (5.5). The proof is completed.

Theorem 5.3: Let $\gamma : I \rightarrow \mathbb{P}$ be a biharmonic curve parametrized by arc length. If C_γ is a focal curve of γ , then the parametric equations of C_γ in terms of τ are

$$\begin{aligned} \tilde{x}^1(s) = & -\frac{c_1 \sin^2 \varphi}{2\sqrt{1-\tau^2}} s^2 + (\bar{a}_1 - \cos \varphi) s + \bar{a}_2 + a_1 \\ \tilde{x}^2(s) = & a_2 - \frac{\sin^3 \varphi}{1-\tau^2 - \sin^4 \varphi} e^{-s \cos \varphi + a_1} (\Omega \cos[\Omega s + a] + [-\Omega + \cos \varphi] \sin[\Omega s + a]) + \\ & \frac{c_1 \sin \varphi}{\sqrt{1-\tau^2}} e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} (\Omega \sin[\Omega s + a] + \cos \varphi \cos[\Omega s + a]) + \\ & \frac{c_1 \sin \varphi}{\sqrt{1-\tau^2}} e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} (-\Omega \cos[\Omega s + a] + \cos \varphi \sin[\Omega s + a]), \\ \tilde{x}^3(s) = & a_3 - \frac{\sin^3 \varphi}{1-\tau^2 - \sin^4 \varphi} e^{-s \cos \varphi + a_1} (-\cos \varphi \cos[\Omega s + a] + [\Omega s + a] \sin[\Omega s + C]) - \\ & - \frac{c_1 \sin \varphi}{\sqrt{1-\tau^2}} e^{-\frac{\sin^2 \varphi}{2} s^2 + \bar{a}_1 s + \bar{a}_2} (-\Omega \cos[\Omega s + a] + \cos \varphi \sin[\Omega s + a]), \end{aligned} \quad (5.11)$$

Where $a, \bar{a}_1, \bar{a}_2, a_1, a_2, a_3$ are constants of integration and $\Omega = \frac{\sqrt{\cos^2 \varphi - \tau^2}}{\sin \varphi}$.

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